

gazebo_ros_control
::RobotHWSim



```
graph BT; A[mia::MiaHWSim] --> B[gazebo_ros_control::RobotHWSim]
```

The diagram consists of two rectangular boxes. The top box is white with a thin black border and contains the text 'gazebo_ros_control' on the first line and '::RobotHWSim' on the second line. The bottom box is gray with a thick black border and contains the text 'mia::MiaHWSim'. A blue arrow points vertically from the top center of the bottom box to the bottom center of the top box.

mia::MiaHWSim